Connect Tech

BOARD SUPPORT PACKAGE

For Connect Tech NVIDIA® Jetson AGX Orin™ Carriers

BSP Version: ORIN-AGX-ANVILRX-36.3.0
Last Updated: 2025/08/05

1. Introduction

This Board Support Package adds support for the Connect Tech Jetson AGX Orin™ family of carrier boards to Linux4Tegra. It includes any extra files required to use all the features of Connect Tech carriers.

Please check Section 3 for supported features for your board and Section 9 for the changes made between versions. You can check which version of the BSP you have installed by running:

cat /etc/cti/CTI-L4T.version

Check for the Latest Version of the CTI-L4T BSP at:
https://connecttech.com/resource-center/l4t-board-support-packages/

2. Requirements

- x86/x64 based host machine running Ubuntu 20.04 or 22.04
- JetPack 6.0 / L4T 36.3.0 installed (see Section 4)
- AGX Orin™ module
- Connect Tech AGX Orin™ Carrier
- USB Cable for flashing

*L4T version can be found in /etc/nv_tegra_release and will look like this:
R36 (release), REVISION: 3.0

3. BSP Features

3.1 Supported Modules in BSP

- AGX Orin™ 32GB
- AGX Orin™ 64GB

- AGX Orin™ Industrial

3.2 Supported Cameras in BSP

- Intel Realsense
- Leopard OWL

3.3 Product Specific Details

AGX206 (Anvil-RX)

- x2 10G ethernet Support.
- x2 2.5G ethernet Support
- CAN Support.
- HDMI Support.
- USB 3.2 Support.
- USB OTG Support.
- I2C Support.
- SPI Support.
- UART Support.
- RS232/485 Support.
- GPIO Support.
- Key E 2230 Wifi/BT.
- TPM Support.
- JCB102 GMSL3 adapter support.

3.4 Limitations and Known Issues

1. Due to firmware and bootloader limitations there is no way to move a module flashed from one AGX Orin™ carrier to another without reflashing. This includes the NVIDIA® Devkit. This means a module flashed for the AGX Orin™ Devkit cannot be used with a CTI carrier without reflashing the module.

2. It has been observed sometimes after flash that the oem setup may fail to launch on the display interface. If this happens, a simple work around is setting a default username and password from Linux_for_Tegra before flashing. run tools/l4t_create_default_user.sh -u <username> -p <password> to achieve this.
Running the oem-setup through the console port, by disconnecting the display port and connecting to the console port before booting the device is also an acceptable workaround.

3. Some Intel WiFi cards may fail to detect intermittently due to a memory access

issue with PCIe controller C7

4. When streaming Intel Realsense cameras, it is recommended not to perform any I2C operations
on the bus where Intel Realsense cameras are connected, as it may disrupt the camera's functionality.

5. This table summarizes the compatibility status of various sensor data stream combinations for Intel Realsense camera.

Combinations	Status
Depth + IR	Supported
Depth + IMU	Supported
RGB + IR	Supported
RGB + IMU	Supported
Depth + RGB	Not Supported
IR + IMU	Not Supported

NOTE: A separate DRGB device tree configuration is available that supports simultaneous Depth and RGB streams.

6. Intel RealSense will only work on Link A of the GMSL3 deserializer due to pipe limitations.

4. Installation

4.1 Obtaining NVIDIA® Jetpack

Before Installing the BSP you will need to install JetPack 6.0 on the host system using NVIDIA® SDK Manager (section 4.1.1) or from the NVIDIA® Embedded Download Center (section 4.1.2)

4.1.1 Installing JetPack from SDK Manager

Please follow installation steps from kdb373 for Jetpack 4.2+
https://connecttech.com/resource-center/kdb373/

4.1.2 Installing JetPack from NVIDIA® Embedded Download Center

1. Create a new directory for installing the Jetpack. Referred to as <BSP_ROOT> in these instructions.

2. Go to Jetpack Release Page https://developer.nvidia.com/embedded/jetson-linux-r3630

3. Download the "L4T Driver Package (BSP)" and "Sample Root Filesystem" files for AGX Orin™

4. Put the "L4T Driver Package (BSP)" and "Sample Root Filesystem" in <BSP_ROOT>. Afterwards, you should have the following files in <BSP_ROOT>

- jetson_linux_r36.3.0_aarch64.tbz2
- tegra_linux_sample-root-filesystem_r36.3.0_aarch64.tbz2

5. Extract the "L4T Driver Package" tarball:

cd <BSP_ROOT>
sudo tar -jxf jetson_linux_r36.3.0_aarch64.tbz2

6. You should now have a new directory called Linux_for_Tegra in your <BSP_ROOT> folder. Extract the "Sample Root Filesystem" into Linux_for_Tegra/rootfs.

sudo tar -C Linux_for_Tegra/rootfs/ -xjf tegra_linux_sample-root-filesystem_r36.3.0_aarch64.tbz2

4.2 CTI BSP Installation

1. Copy the CTI-L4T-ORIN-AGX-ANVILRX-36.3.0-V###.tgz package into <BSP_ROOT>/Linux_for_Tegra.

If you are using Nvidia's SDK manager then "<BSP_ROOT>" will be:
~/nvidia/nvidia_sdk/<JetPack_Version>_Linux_JETSON_AGX_ORIN_TARGETS/

Otherwise if manually installing from the NVIDIA® Embedded Download Center <BSP_ROOT> will be the folder created previously

cp CTI-L4T-ORIN-AGX-ANVILRX-36.3.0-V###.tgz <BSP_ROOT>/Linux_for_Tegra

2. Extract the BSP: tar -xzf CTI-L4T-ORIN-AGX-ANVILRX-36.3.0-V###.tgz
cd <BSP_ROOT>/Linux_for_Tegra
sudo tar -xzf CTI-L4T-ORIN-AGX-ANVILRX-36.3.0-V###.tgz

3. Change into the CTI-L4T directory:
cd <BSP_ROOT>/Linux_for_Tegra/CTI-L4T

4. Run the install script (as root or sudo) to automatically install the BSP files to the correct locations:

sudo ./install.sh

#return to Linux_for_Tegra
cd ..

5. The CTI-L4T BSP is now installed on the host system and it should now be able to flash the AGX Orin™ module.

5. Flashing AGX Orin™ Modules

1. Connect the AGX Orin™ and Carrier to the computer via USB, following the instructions in the appropriate manual.

2. Put the system to be flashed into recovery mode, following the instructions in the appropriate manual

3. There are two options for flashing Jetson modules:

Using CTI's automated script:
./cti-flash.sh

Follow the menu and select your desired configuration. Once selected,

the device will start to flash.

Using the Manual Method:

Note do not add the ".conf" file extension to the <config> parameter:

Manual Flash: ./flash.sh cti/<module>/<boardname>/<config> mmcblk0p1

<module> is orin-agx or orin-agxi (orin-agx industrial)

Example:
./flash.sh cti/orin-agx/forge/base mmcblk0p1
./flash.sh cti/orin-agxi/forge/base mmcblk0p1

4. Once the flashing has completed, the AGX Orin™ will reboot

6. Upgrading to a New Package Release

Upgrading L4T or CTI-BSP verisons without reflashing is not currently supported.

7. Switching Profiles on AGX Orin™

1. Open a terminal on the AGX Orin™

2. Run "sudo cti-orin-agx-fdt.sh"

3. Select the profile you wish to switch to from the menu

4. Restart the system

Note: This script updates the dtb by appending/replacing the FDT variable in extlinux.conf

8. Non-volatile Jumper blocks

Included with this BSP is a program called "ds4520". This program will allow you to set the jumper settings for the 3 onboard nonvolatile jumper blocks.

Program usage is as follows:
ds4520 -b [i2c bus#] -a [0xXX i2c address] 0=[0/1/f] 1=[0/1/f] ... 8=[0/1/f] #Set IOs
ds4520 -b 6 -a 0x53 0=0 1=f 2=1 #Set IO0 to low, set IO1 to float, set IO2 to HIGH
ds4520 -b 6 -a 0x53 -g #Print out current GPIO states
ds4520 -b 6 -a 0x53 -w 0 #save states to NV memory and lock
ds4520 -b 6 -a 0x53 -w 1 #unlock eeprom, allow modification

9. Change Log

Version ORIN-AGX-ANVILRX-36.3.0-INTELRS-LI-OWL-V001 Aug. 05 2025

- First release of Intel RS and Li-Owl in ANVIL-RX for Jetpack 6

Contact Connect Tech

If you have any problems, questions or suggestions regarding the Board Support Package and hardware, please feel free to contact Connect Tech Inc.

Contact Information	
Support	Please go to the Connect Tech Resource Center for product manuals, installation guides, device drivers, BSPs and technical tips. Submit your technical support questions to our support engineers. Technical Support representatives are available Monday through Friday, from 8:30 a.m. to 5:00 p.m. Eastern Standard Time.
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