

BOARD SUPPORT PACKAGE

For Connect Tech NVIDIA® Jetson ORIN-AGX Carriers

BSP Version: ORIN-AGX-36.4.0 V005
Last Updated: 2025/02/13

1. Introduction

This Board Support Package adds support for the Connect Tech Jetson AGX Orin™ family of carrier boards to Linux4Tegra. It includes any extra files required to use all the features of Connect Tech carriers.

Please check Section 3 for supported features for your board and Section 8 for the changes made between versions. You can check which version of the BSP you have installed by running:

```
cat /etc/cti/CTI-L4T.version
```

Check for the Latest Version of the CTI-L4T BSP at:
<https://connecttech.com/resource-center/l4t-board-support-packages/>

2. Requirements

- x86/x64 based host machine running Ubuntu 20.04 or 22.04
- JetPack 6.1 / L4T 36.4.0 installed (see Section 4)
- AGX Orin™ module
- Connect Tech AGX Orin™ Carrier
- USB Cable for flashing

*L4T version can be found in /etc/nv_tegra_release and will look like this:
R36 (release), REVISION: 4.0

3. BSP Features

3.1 Supported Modules in BSP

- AGX Orin™ 32GB
- AGX Orin™ 64GB
- AGX Orin™ Industrial

3.2 Supported Cameras in BSP

- Leopard IMX390
- Stereolabs ZEDX
- Leopard OWL
- ECON STURDeCAM31
- ECON NileCam82
- Leopard AR0234CSC/AR0234CSM
- Framos GMSL IMX678
- Framos GMSL IMX568

3.2.1 Installing ZED X camera SDK

The ZED SDK is required to operate the ZED X camera. To use the SDK, Nvidia's CUDA, along with a few other dependencies, must first be installed (It is not installed automatically with this BSP).

To install these dependencies, run this command:

```
"sudo apt install zstd libqt5network5 libqt5opengl5 libqt5sql5 libqt5xml5 cuda"
```

The ZED SDK can then be downloaded onto the AGX Orin™ from the Stereolabs website here: <https://www.stereolabs.com/developers/release/>

Click on "SDK Downloads", then the link for "ZED SDK for JetPack 6.0 (L4T 36.3)".

Note: ZED X drivers are already included in this BSP and do not need to be downloaded.

Once you have downloaded the executable onto your AGX Orin™ system, follow the rest of the instructions under "Download and Install the ZED SDK" at this link: <https://www.stereolabs.com/docs/installation/jetson/>

Additional questions about the SDK and camera applications can be answered by Stereolabs at <https://support.stereolabs.com/hc/en-us/>

3.3 Product Specific Details

AGX201 (Forge)

- 10G and 1G ethernet Support.
- CAN Support.
- Display Port Support.
- USB 3.2 Support.
- USB OTG Support.
- I2C Support.
- SPI Support.
- UART Support.
- RS232/485 Support.
- GPIO Support.
- M.2 pcie Support.
- Key E 2230 Wifi/BT.
- Key B 3042/3052 LTE/5G with micro SIM.
- Micro SD support.
- Oculink support
- Endpoint Mode not Supported
- JCB002 GMSL adapter support.
- JCB003 adapter support.

ESG620 (Anvil)

- 10G and 1G ethernet Support.
- CAN Support.
- Display Port Support.
- USB 3.2 Support.
- USB OTG Support.
- I2C Support.
- SPI Support.
- UART Support.
- RS232/485 Support.
- GPIO Support.
- M.2 pcie Support.
- Key E 2230 Wifi/BT.
- Key B 3042/3052 LTE/5G with micro SIM.
- Micro SD support.
- Oculink support
- Endpoint Mode not Supported
- JCB002 GMSL adapter support.
- JCB003 adapter support.

AGX202/AGX203 (Rogue-Orin/ Rogue-RX)

- x2 10G ethernet Support.
- CAN Support.
- HDMI Support.
- USB 3.2 Support.
- USB OTG Support.
- I2C Support.
- SPI Support.
- UART Support.
- GPIO Support.
- M.2 pcie Support.
- Key E 2230 Wifi/BT.
- Micro SD support.
- JCB002 GMSL adapter support.
- JCB003 adapter support.

3.4 Limitations and Known Issues

1. Due to firmware and bootloader limitations there is no way to move a module flashed from one AGX Orin™ carrier to another without reflashing. This includes the NVIDIA® Devkit. This means a module flashed for the AGX Orin™ Devkit cannot be used with a CTI carrier without reflashing the module.

2. It has been observed sometimes after flash that the oem setup may fail to launch on the display interface. If this happens, a simple work around is setting a default username and password from Linux_for_Tegra before flashing.
run `tools/l4t_create_default_user.sh -u <username> -p <password>`
to achieve this.

Running the oem-setup through the console port, by disconnecting the display port and connecting to the console port before booting the device is also an acceptable workaround.

3. Master mode (internal trigger) for the Leopard OWL and Hawk is currently running at 45FPS, even though the streaming mode is set to 30FPS in the device tree. By default we are shipping configs for Hawk and OWL to use trigger mode so that the appropriate FPS can be achieved.

```
example. set pwm01 to 30FPS on Forge before streaming
cd /sys/class/pwm/pwmchip3
echo 0 > export
echo 33333333 > pwm0/period
echo 1000000 > pwm0/duty_cycle
```

You may also use this technique to achieve a custom trigger rate.

4. Some Intel WiFi cards may fail to detect intermittently due to a memory access issue with PCIe controller C7

5. Mode 0 on NileCAM82 has been observed to instantly close with some gstreamer commands that work with mode 1 on the camera. The command
`"gst-launch-1.0 nvarguscamerasrc sensor-id=<x> sensor-mode=0 ! "video/x-raw(memory:NVMM), height=2160, width=3840, framerate=26/1" ! nvvidconv ! xvimagesink"`
was found to successfully stream mode 0.

6. With the Framos GMSL cameras, you must set the `data_rate v4l2` control to 891mbps or 594mbps

i.e. `v4l2-ctl -d /dev/videoX -c data_rate=1 # set 891mbps data_rate`

7. With the Framos GMSL cameras, streaming all 8 cameras simultaneously provokes an issue with nvargus. You may stream up to 7 cameras simultaneously before the issue takes effect.

4. Installation

4.1 Obtaining NVIDIA® Jetpack

Before installing the BSP you will need to install JetPack 6.1 on the host system using NVIDIA® SDK Manager (section 4.1.1) or from the NVIDIA® Embedded Download Center (section 4.1.2)

4.1.1 Installing JetPack from SDK Manager

Please follow installation steps from kdb373 for Jetpack 4.2+ <https://connecttech.com/resource-center/kdb373/>

4.1.2 Installing JetPack from NVIDIA® Embedded Download Center

1. Create a new directory for installing the Jetpack. Referred to as `<BSP_ROOT>` in these instructions.
2. Go to Jetpack Release Page <https://developer.nvidia.com/embedded/jetson-linux-r3640>
3. Download the "L4T Driver Package (BSP)" and "Sample Root Filesystem" files for AGX Orin™
4. Put the "L4T Driver Package (BSP)" and "Sample Root Filesystem" in `<BSP_ROOT>`. Afterwards, you should have the following files in `<BSP_ROOT>`
 - `jetson_linux_r36.4.0_aarch64.tbz2`

- `tegra_linux_sample-root-filesystem_r36.4.0_aarch64.tbz2`

5. Extract the "L4T Driver Package" tarball:

```
cd <BSP_ROOT>
sudo tar -jxf jetson_linux_r36.4.0_aarch64.tbz2
```

6. You should now have a new directory called `Linux_for_Tegra` in your `<BSP_ROOT>` folder. Extract the "Sample Root Filesystem" into `Linux_for_Tegra/rootfs`.

```
sudo tar -C Linux_for_Tegra/rootfs/ -xjf tegra_linux_sample-root-filesystem_r36.4.0_aarch64.tbz2
```

4.2 CTI BSP Installation

1. Copy the `CTI-L4T-ORIN-AGX-RT-36.4.0-V###.tgz` package into `<BSP_ROOT>/Linux_for_Tegra`.

If you are using Nvidia's SDK manager then "`<BSP_ROOT>`" will be:
`~/nvidia/nvidia_sdk/<JetPack_Version>_Linux_JETSON_AGX_ORIN_TARGETS/`

Otherwise if manually installing from the NVIDIA® Embedded Download Center `<BSP_ROOT>` will be the folder created previously

```
cp CTI-L4T-ORIN-AGX-RT-36.4.0-V###.tgz <BSP_ROOT>/Linux_for_Tegra
```

2. Extract the BSP: `tar -xzf CTI-L4T-ORIN-AGX-RT-36.4.0-V###.tgz`
`cd <BSP_ROOT>/Linux_for_Tegra`
`sudo tar -xzf CTI-L4T-ORIN-AGX-RT-36.4.0-V###.tgz`

3. Change into the CTI-L4T directory:
`cd <BSP_ROOT>/Linux_for_Tegra/CTI-L4T`

4. Run the install script (as root or sudo) to automatically install the BSP files to the correct locations:

```
sudo ./install.sh
#return to Linux_for_Tegra
cd ..
```

5. The CTI-L4T BSP is now installed on the host system and it should now be able to flash the AGX Orin™ module.

5. Flashing AGX Orin™ Modules

1. Connect the AGX Orin™ and Carrier to the computer via USB, following the instructions in the appropriate manual.

2. Put the system to be flashed into recovery mode, following the instructions in the appropriate manual

3. There are two options for flashing Jetson modules:

Using CTI's automated script:

```
./cti-flash.sh
```

Follow the menu and select your desired configuration. Once selected,

the device will start to flash.

Using the Manual Method:

Note do not add the ".conf" file extension to the <config> parameter:

Manual Flash: `./flash.sh cti/<module>/<boardname>/<config> mmcblk0p1`

<module> is orin-agx or orin-agxi (orin-agx industrial)

Example:

```
./flash.sh cti/orin-agx/forge/base mmcblk0p1
```

```
./flash.sh cti/orin-agxi/forge/base mmcblk0p1
```

4. Once the flashing has completed, the AGX Orin™ will reboot

6. Upgrading to a New Package Release

Upgrading L4T or CTI-BSP versions without reflashing is not currently supported.

7. Switching Profiles on AGX Orin™

1. Open a terminal on the AGX Orin™

2. Run "sudo cti-orin-agx-fdt.sh"

3. Select the profile you wish to switch to from the menu

4. Restart the system

Note: This script updates the dtb by appending/replacing the FDT variable in extlinux.conf

8. Non-volatile Jumper Blocks (Anvil-RX)

Included with this BSP is a program called "ds4520". This program will allow you to set the jumper settings for the 3 onboard nonvolatile jumper blocks.

Program usage is as follows:

```
ds4520 -b [i2c bus#] -a [0xXX i2c address] 0=[0/1/f] 1=[0/1/f] ... 8=[0/1/f] #Set IOs
ds4520 -b 6 -a 0x53 0=0 1=f 2=1 #Set IO0 to low, set IO1 to float, set IO2 to HIGH
ds4520 -b 6 -a 0x53 -g #Print out current GPIO states
ds4520 -b 6 -a 0x53 -w 0 #save states to NV memory and lock
ds4520 -b 6 -a 0x53 -w 1 #unlock eeprom, allow modification
```

9. Change Log

Version ORIN-AGX-36.4.0-V005 Feb 13, 2025

- Added Framos GMSL IMX568 & IMX678 support to Forge and Rogue-Orin

Version ORIN-AGX-36.4.0-V004 Jan. 6, 2025

- First release of ANVIL-RX for Jetpack 6

Version ORIN-AGX-36.4.0-V003 Dec. 3, 2024

- Added support for ECON NileCam82
- Added support for Leopard Imaging AR0234CSC and AR0234CSM

Version ORIN-AGX-36.4.0-V002 Oct. 29, 2024

- Added support for ECON STURDeCAM31

Version ORIN-AGX-36.4.0-V001 Oct. 22, 2024

- Initial Release of AGX Orin™ on Jetpack 6.1 l4t 36.4.0.
- Added support for JCB003 adapter

Contact Connect Tech

If you have any problems, questions or suggestions regarding the Board Support Package and hardware, please feel free to contact Connect Tech Inc.

Contact Information	
Support	<p>Please go to the Connect Tech Resource Center for product manuals, installation guides, device drivers, BSPs and technical tips.</p> <p>Submit your technical support questions to our support engineers. Technical Support representatives are available Monday through Friday, from 8:30 a.m. to 5:00 p.m. Eastern Standard Time.</p>
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